## Unit 5: Cubic Splines

Let $K=\left\{x_{0}, \ldots, x_{m}\right\}$ be a set of given knots with

$$
a=x_{0}<x_{1}<\cdots<x_{m}=b
$$

Definition. [11.2] A function $s \in C^{2}[a, b]$ is called a cubic spline on $[a, b]$, if $s$ is a cubic polynomial $s_{i}$ in each interval $\left[x_{i}, x_{i+1}\right]$.

It is called a cubic interpolating spline if $s\left(x_{i}\right)=y_{i}$ for given values $y_{i}$.

## 5.1: Cubic Splines

Interpolating cubic splines need two additional conditions to be uniquely defined

Definition. [11.3] An cubic interpolatory spilne $s$ is called a natural spline if

$$
s^{\prime \prime}\left(x_{0}\right)=s^{\prime \prime}\left(x_{m}\right)=0
$$

## 5.2: Cubic Splines - Construction

We construct an interpolating in a different but equivalent way than in the textbook:

Ansatz for $m$ the piecewise polynomials

$$
s_{i}(x)=a_{i}\left(x-x_{i}\right)^{3}+b_{i}\left(x-x_{i}\right)^{2}+c_{i}\left(x-x_{i}\right)+d_{i}
$$

By fixing the $4 m$ free coefficients $a_{i}, b_{i}, c_{i}, d_{i}, i=0: m-1$ the entire spline is fixed.

## 5.3: Cubic Splines-Construction

We need $4 m$ conditions to fix the coefficients
(1) $s_{i}\left(x_{i}\right)=y_{i}$,
for $i=0: m-1$,
(2) $s_{m-1}=y_{m}$,

1 condition
(3) $s_{i}\left(x_{i+1}\right)=s_{i+1}\left(x_{i+1}\right)$,
for $i=0: m-2$,
(4) $s_{i}^{\prime}\left(x_{i+1}\right)=s_{i+1}^{\prime}\left(x_{i+1}\right)$,
for $i=0: m-2$,
(5) $s_{i}^{\prime \prime}\left(x_{i+1}\right)=s_{i+1}^{\prime \prime}\left(x_{i+1}\right)$,
for $i=0: m-2$,
These are $4 m-2$ conditions. We need two extra.
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## 5.4: Cubic Splines-Boundary Conditions

We can define two extra boundary conditions. One has several alternatives:

Natural Spline
End Slope Spline
Periodic Spline

$$
s_{0}^{\prime \prime}\left(x_{0}\right)=0 \text { and } s_{m-1}^{\prime \prime}\left(x_{m}\right)=0
$$

$$
s_{0}^{\prime}\left(x_{0}\right)=y_{0}^{\prime} \text { and } s_{m-1}^{\prime}\left(x_{m}\right)=y_{m}^{\prime}
$$

$$
s_{0}^{\prime}\left(x_{0}\right)=s_{m-1}^{\prime}\left(x_{m}\right) \text { and } s_{0}^{\prime \prime}\left(x_{0}\right)=s_{m-1}^{\prime \prime}\left(x_{m}\right)
$$

Not-a-Knot Spline

$$
s_{0}^{\prime \prime \prime}\left(x_{1}\right)=s_{1}^{\prime \prime \prime}\left(x_{1}\right) \text { and } s_{m-2}^{\prime \prime \prime}\left(x_{m-1}\right)=s_{m-1}^{\prime \prime \prime}\left(x_{m-1}\right)
$$

We consider here natural splines.
MATLAB uses splines with a not-a-knot condition.

## 5.5: Natural Splines Construction

$$
s_{i}(x)=a_{i}\left(x-x_{i}\right)^{3}+b_{i}\left(x-x_{i}\right)^{2}+c_{i}\left(x-x_{i}\right)+d_{i}
$$

Let $h=x_{i+1}-x_{i}$ equidistant spacing

$$
\begin{aligned}
s_{i}^{\prime}\left(t_{i+1}\right) & =3 a_{i} h^{2}+2 b_{i} h+c_{i} \\
s_{i}^{\prime \prime}\left(t_{i+1}\right) & =6 a_{i} h+2 b_{i}
\end{aligned}
$$

From Condition (1) we get $d_{i}=y_{i}$.

We introduce new variables for the second derivatives at $x_{i}$, i.e.

$$
\sigma_{i}:=s^{\prime \prime}\left(x_{i}\right)=6 a_{i}\left(x_{i}-x_{i}\right)+2 b_{i}=2 b_{i} \quad i=0: m
$$

## 5.6: Natural Splines Construction

Thus $b_{i}=\frac{\sigma_{i}}{2}$.
From

$$
\sigma_{i+1}=6 a_{i} h+2 b_{i}
$$

and Condition (5) we get

$$
a_{i}=\frac{\sigma_{i+1}-\sigma_{i}}{6 h}
$$

By Condition (3) we get

$$
y_{i+1}=a_{i} h^{3}+b_{i} h^{2}+c_{i} h+y_{i} .
$$

## 5.7: Natural Splines Construction

$\ldots$ and after inserting the hight-lighted expressions for $a_{i}$ and $b_{i}$ we get

$$
y_{i+1}=\left(\frac{\sigma_{i+1}-\sigma_{i}}{6 h}\right) h^{3}+\frac{\sigma_{i}}{2} h^{2}+c_{i} h+y_{i} .
$$

From that we get $c_{i}: \quad c_{i}=\frac{y_{i+1}-y_{i}}{h}-h \frac{2 \sigma_{i}+\sigma_{i+1}}{6}$

Using now Condition (4) gives a relation between $c_{i}$ and $c_{i+1}$

$$
c_{i+1}=3 a_{i} h^{2}+2 b_{i} h+c_{i} .
$$

## 5.8: Natural Splines Construction

Inserting now the expressions for $a_{i}, b_{i}$ and $c_{i}$, using Condition (2) and simplifying finally gives the central recursion formula:

$$
\sigma_{i-1}+4 \sigma_{i}+\sigma_{i+1}=6\left(\frac{y_{i+1}-2 y_{i}+y_{i-1}}{h^{2}}\right)
$$

with $i=1, \ldots, m-1$.

We consider now natural boundary conditions

$$
\sigma_{0}=\sigma_{m}=0
$$

## 5.9: Natural Splines Construction

Finally we rewrite this all a system of linear equations

$$
\left(\begin{array}{ccccc}
4 & 1 & & & \\
1 & 4 & 1 & & \\
& 1 & \ddots & 1 & \\
& & & \ddots & 1 \\
& & & 1 & 4
\end{array}\right)\left(\begin{array}{c}
\sigma_{1} \\
\sigma_{2} \\
\sigma_{3} \\
\vdots \\
\sigma_{m-1}
\end{array}\right)=\frac{6}{h^{2}}\left(\begin{array}{c}
y_{2}-2 y_{1}+y_{0} \\
y_{3}-2 y_{2}+y_{1} \\
\vdots \\
\vdots \\
y_{n}-2 y_{n-1}+y_{n-2}
\end{array}\right)
$$

First, this system is solved and then the coefficients $a_{i}, b_{i}, c_{i}, d_{i}$ are determined by the high-lighted equations.

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