Unit 5: Cubic Splines

Let $K = \{x_0, \ldots, x_m\}$ be a set of given knots with

$$a = x_0 < x_1 < \dots < x_m = b$$

Definition. [11.2] A function $s \in C^2[a, b]$ is called a cubic spline on [a, b], if s is a cubic polynomial s_i in each interval $[x_i, x_{i+1}]$.

It is called a cubic interpolating spline if $s(x_i) = y_i$ for given values y_i .

5.1: Cubic Splines

Interpolating cubic splines need two additional conditions to be uniquely defined

Definition. [11.3] An cubic interpolatory spilne s is called a natural spline if

$$s''(x_0) = s''(x_m) = 0$$

5.2: Cubic Splines - Construction

We construct an interpolating in a different but equivalent way than in the textbook:

Ansatz for m the piecewise polynomials

$$s_i(x) = a_i(x - x_i)^3 + b_i(x - x_i)^2 + c_i(x - x_i) + d_i$$

By fixing the 4m free coefficients $a_i, b_i, c_i, d_i, i = 0 : m - 1$ the entire spline is fixed.

5.3: Cubic Splines-Construction

We need 4m conditions to fix the coefficients

(1)
$$s_i(x_i) = y_i$$
, for $i = 0 : m - 1$,

(2)
$$s_{m-1} = y_m$$
, 1 condition

- (3) $s_i(x_{i+1}) = s_{i+1}(x_{i+1})$, for i = 0 : m 2,
- (4) $s'_i(x_{i+1}) = s'_{i+1}(x_{i+1})$, for i = 0 : m 2,
- (5) $s''_i(x_{i+1}) = s''_{i+1}(x_{i+1})$, for i = 0 : m 2,

These are 4m - 2 conditions. We need two extra. C. Führer: FMN081-2005

5.4: Cubic Splines-Boundary Conditions

We can define two extra boundary conditions. One has several alternatives:

 Natural Spline
 $s''_0(x_0) = 0$ and $s''_{m-1}(x_m) = 0$

 End Slope Spline
 $s'_0(x_0) = y'_0$ and $s'_{m-1}(x_m) = y'_m$

 Periodic Spline
 $s'_0(x_0) = s'_{m-1}(x_m)$ and $s''_0(x_0) = s''_{m-1}(x_m)$

 Not-a-Knot Spline
 $s'''_0(x_1) = s'''_1(x_1)$ and $s'''_{m-2}(x_{m-1}) = s'''_{m-1}(x_{m-1})$

We consider here natural splines. MATLAB uses splines with a not-a-knot condition.

5.5: Natural Splines Construction

 $s_i(x) = a_i(x-x_i)^3 + b_i(x-x_i)^2 + c_i(x-x_i) + d_i$ Let $h = x_{i+1} - x_i$ equidistant spacing

$$s'_{i}(t_{i+1}) = 3a_{i}h^{2} + 2b_{i}h + c_{i}$$

 $s''_{i}(t_{i+1}) = 6a_{i}h + 2b_{i}$

From Condition (1) we get $d_i = y_i$.

We introduce new variables for the second derivatives at x_i , i.e.

$$\sigma_i := s''(x_i) = 6a_i(x_i - x_i) + 2b_i = 2b_i \quad i = 0:m$$

5.6: Natural Splines Construction

(Cont.)

Thus
$$b_i = \frac{\sigma_i}{2}$$

From

$$\sigma_{i+1} = 6a_ih + 2b_i.$$

and Condition (5) we get

$$a_i = \frac{\sigma_{i+1} - \sigma_i}{6h}$$

By Condition (3) we get

$$y_{i+1} = a_i h^3 + b_i h^2 + c_i h + y_i.$$

5.7: Natural Splines Construction

(Cont.)

... and after inserting the hight-lighted expressions for a_i and b_i we get

$$y_{i+1} = \left(\frac{\sigma_{i+1} - \sigma_i}{6h}\right)h^3 + \frac{\sigma_i}{2}h^2 + c_ih + y_i.$$

From that we get
$$c_i$$
: $c_i = \frac{y_{i+1}-y_i}{h} - h \frac{2\sigma_i + \sigma_{i+1}}{6}$.

Using now Condition (4) gives a relation between c_i and c_{i+1}

$$c_{i+1} = 3a_ih^2 + 2b_ih + c_i.$$

5.8: Natural Splines Construction (Cont.)

Inserting now the expressions for a_i, b_i and c_i , using Condition (2) and simplifying finally gives the central recursion formula:

$$\sigma_{i-1} + 4\sigma_i + \sigma_{i+1} = 6 \left(\frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} \right)$$
 with $i = 1, \dots, m-1$.

We consider now natural boundary conditions

$$\sigma_0 = \sigma_m = 0.$$

5.9: Natural Splines Construction



Finally we rewrite this all a system of linear equations

$$\begin{pmatrix} 4 & 1 & & & \\ 1 & 4 & 1 & & \\ & 1 & \ddots & 1 & \\ & & & \ddots & 1 \\ & & & & 1 & 4 \end{pmatrix} \begin{pmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \vdots \\ \sigma_{m-1} \end{pmatrix} = \frac{6}{h^2} \begin{pmatrix} y_2 - 2y_1 + y_0 \\ y_3 - 2y_2 + y_1 \\ \vdots \\ y_n - 2y_{n-1} + y_{n-2} \end{pmatrix}$$

First, this system is solved and then the coefficients a_i, b_i, c_i, d_i are determined by the high-lighted equations.